



Developing a Distributed Oceanographic Match-up Service

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Overview

- Goal: To develop a distributed data service (a.k.a DOMS) to match satellite and in situ marine observations to support platform comparisons, cross-calibration, validation, and quality control
- Prototype is in development
 - Target for completion early 2017
 - Test version hopefully available by July 2016



Overview



Users will be able to select a region, time period, and variable (SST, salinity, winds) from a select subset of satellite and in situ data sets. They will receive matched data along with complementary metadata to support their research goals.

Satellite Data

The Physical Oceanography Distributed Active Archive Center (PO.DAAC) is the premier data center for NASA satellite measurements focused on ocean surface topography (OST), sea surface temperature (SST), ocean winds, sea surface salinity (SSS), gravity, ocean circulation and sea ice.



Field Experiments

Salinity Processes in the Upper Ocean Regional Study (SPURS) is a pair of oceanographic field experiments addressing the essential role of the ocean in the global water cycle using a plethora of in situ oceanographic equipment and technology, including research ships, floats, drifters, autonomous gliders and moorings.

Distributed Oceanographic Match-up Service

DOMS



PORTAL
SECURE WEB INTERFACE - 1 PASSWORD
NAME: _____
PASSWORD: _____



Ship Data

The Shipboard Automated Meteorological and Oceanographic System (SAMOS) initiative provides routine access to accurate, high-quality marine meteorological and near-surface oceanographic observations from research vessels. Variables include SST, SLP, winds and air temperature.

Surface Marine Data

The National Center for Atmospheric Research (NCAR) hosts the International Comprehensive Ocean-Atmospheric Data Set, the most comprehensive archive of global marine surface climate observations available. Variables include SST, SLP, air temperature, wind speed, cloud amount, and others.

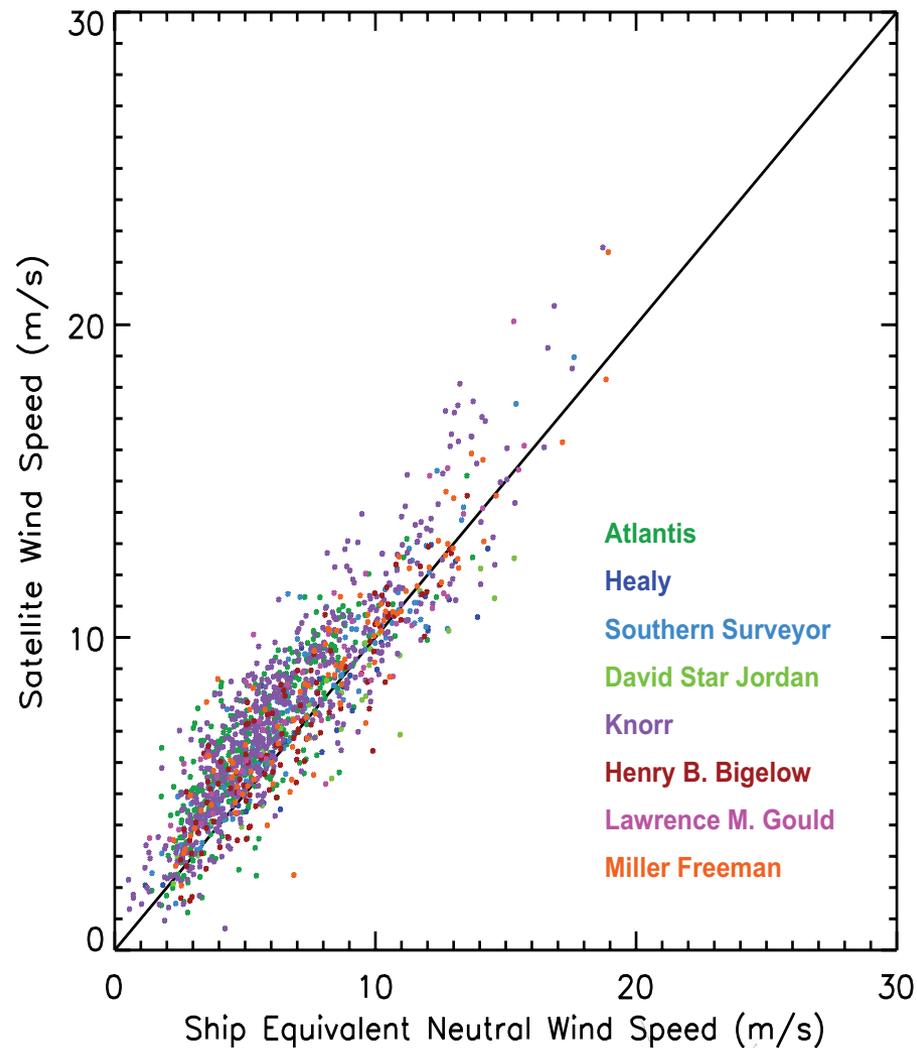




Use Cases for DOMS

Defined Use Cases

- Satellite Cal/Val and algorithm development
- Decision support
 - Planning field campaigns
 - Real-time operational activities
- Scientific investigation
 - Process studies
 - Model assimilation services
 - User friendly interface to support student research
- Alternate matching
 - Satellite to satellite
 - Satellite/in situ to model





In situ to Satellite Data Matching

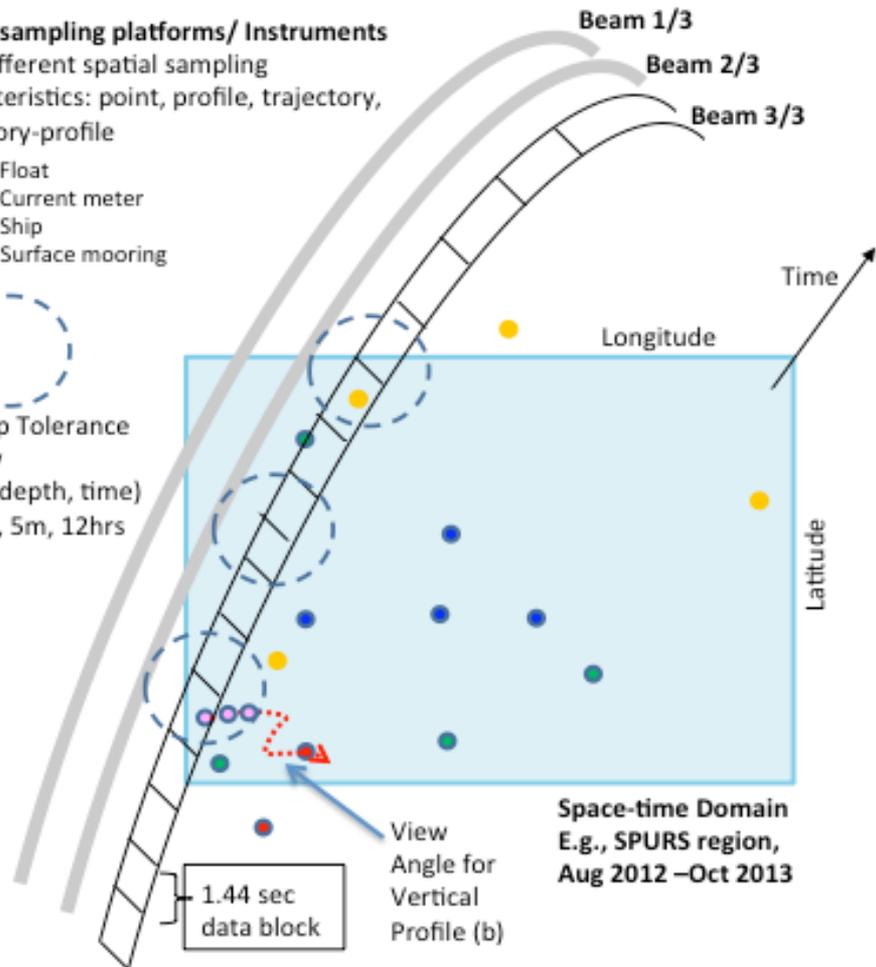
Horizontal/Top-Down View

In-situ sampling platforms/ Instruments with different spatial sampling characteristics: point, profile, trajectory, trajectory-profile

- - Float
- - Current meter
- - Ship
- - Surface mooring

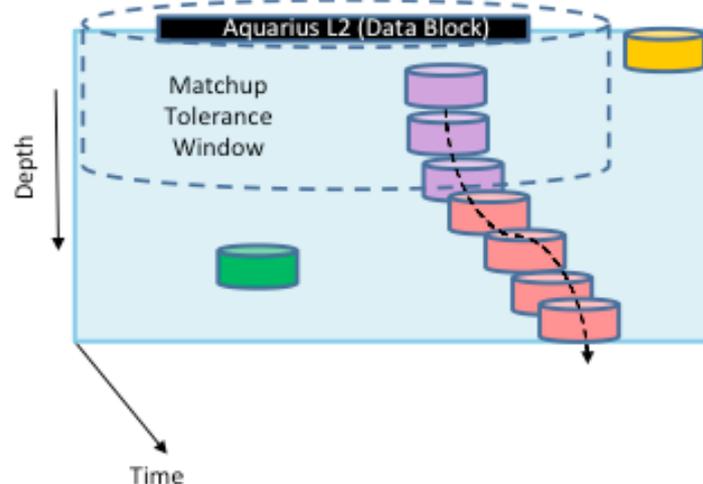


Matchup Tolerance Window (radius, depth, time)
Eg. 6km, 5m, 12hrs



- Example of data matching for Aquarius swath data
- Input space-time domain (including depth) and tolerance window
- Return only matches within criteria

Vertical Profile View

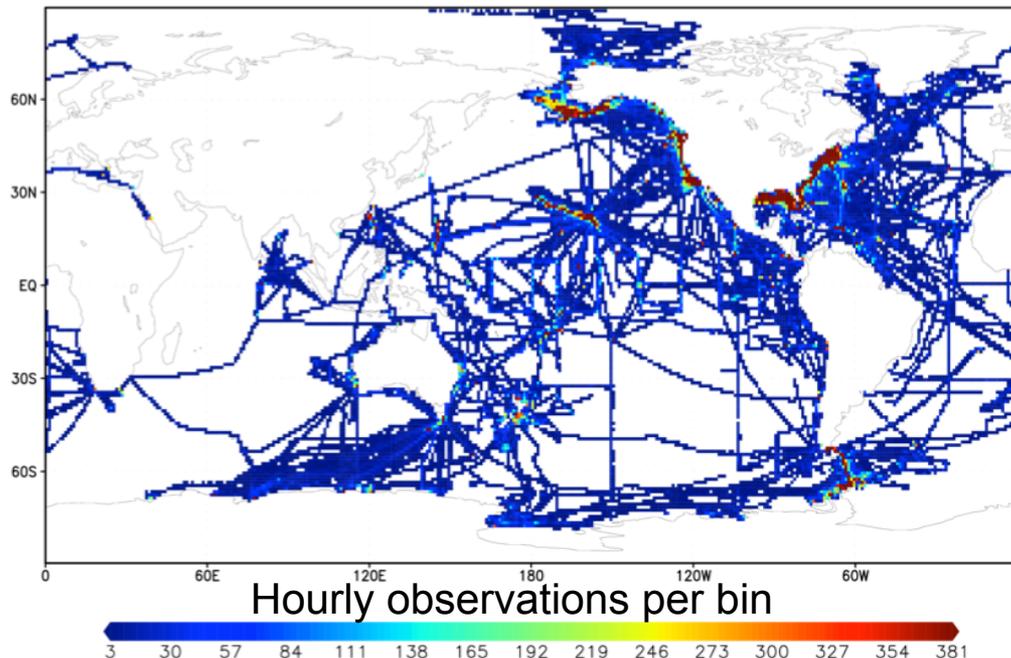




In situ data: SAMOS

- Shipboard Automated Meteorological and Oceanographic System (SAMOS) initiative provides high-quality underway data from research vessels.
- Hosted at FSU/COAPS.
- ~30 vessels participating in FY2014
 - Vessels operated by WHOI, SIO, UH, UW, BIOS, NOAA, USCG, USAP, IMOS, SO, LUMCON
 - ~30-40K one-minute observations/month/vessel

SAMOS Data Density: 2005-2014



- Data include routine navigation (position, course, heading, speed), meteorology (wind, air temperature, humidity, pressure, rainfall, radiation), and oceanography (sea temperature and salinity).
- All data undergo scientific quality control.





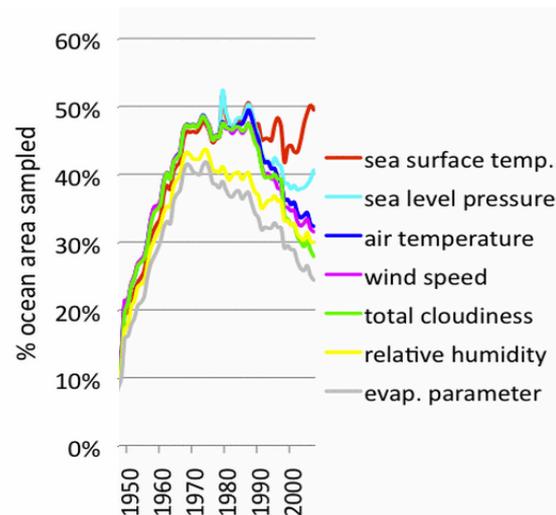
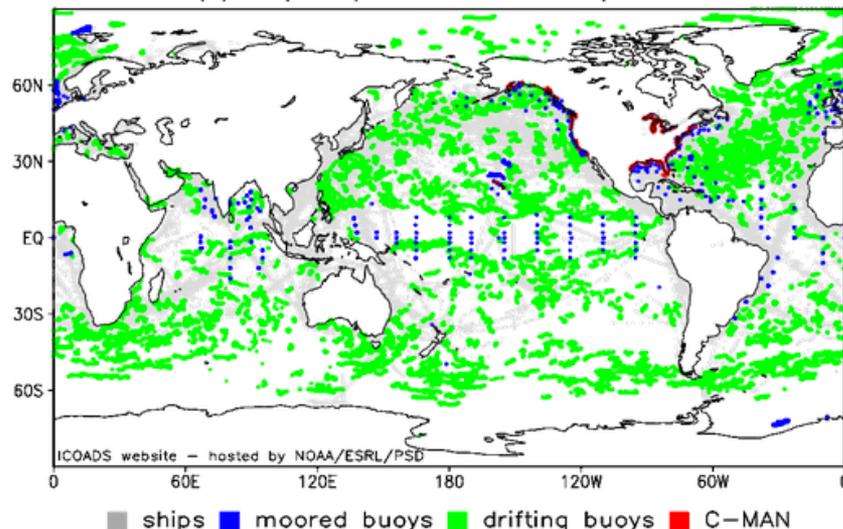
In situ data: ICOADS

ICOADS Release 3.0

- Global coverage from ocean observing systems
 - Approximately 3M records per month
 - VOS and R/V mainly from WOD and GOSUD
 - Moored buoys: GTMBA and national systems
 - Drifting buoys: surface and ARGO
- Percent of ocean coverage per year varies by parameter
- Updated monthly with NCEP + NCDC GTS data streams
- Each record has UID and observing system tracking metadata
- Salinity added as a new parameter

Note: Illustrative figures are produced from Release 2.5, the current operational archive

(b) map of platform mixture: Apr 2015





In situ data: SPURS-1

- NASA-funded oceanographic field campaign and science salinity process study in the North Atlantic maximum salinity region (2012-13).

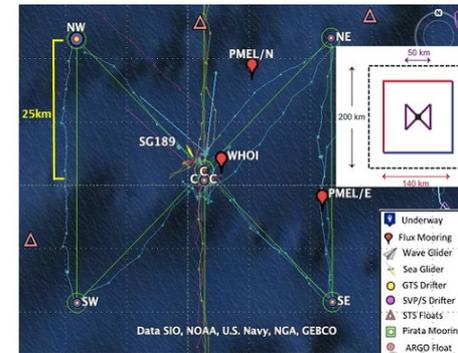
- AIM:

- Elucidate key mechanisms responsible for near-surface salinity variations
- Quantify the relative significance of circulation, evaporation, precipitation over a range of scales over the open ocean.
- Surface Salinity observations valuable for Aquarius/SAC-D Cal/Val

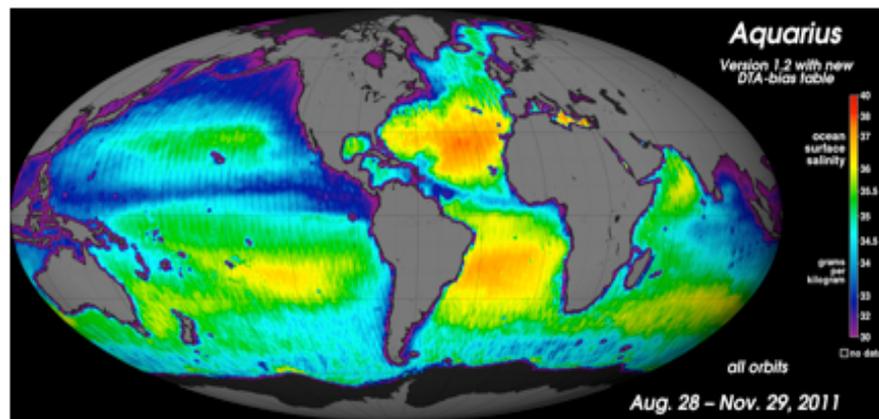
Ship (cruise #)	Dates	Country	Chief Scientist
Thalassa	16-Aug - 13-Sep-2012	France	<u>Reverdin</u>
Knorr (209)	6-Sep - 9-Oct-2012	US	Schmitt
Endeavor-1 (522)	15-Mar - 15-Apr-2013	US	Schmitt
Sarmiento	14-Mar - 10-Apr-2013	Spain	Font
Endeavor-2 (533)	19-Sep - 13-Oct-2013	US	<u>Fratantoni</u>

- Field campaign

- Series of 5 cruises
- Advanced sampling technologies deployed in a nested design
 - 900 x 800-mile square study area centered at 25° N, 38° W.
- Natively heterogeneous formats for 15 datasets converted to NODC NetCDF standard by SPURS-DMT
- Archived at the PO.DAAC, Discoverable & Distributed publicly as of 5/11/2015
 - PO.DAAC SPURS Mission Page: <http://podaac.jpl.nasa.gov/spurs>
 - SPURS-1 Dataset Catalog collection: <http://podaac.jpl.nasa.gov/datasetlist?ids=Collections&values=SPURS-1&view=list>



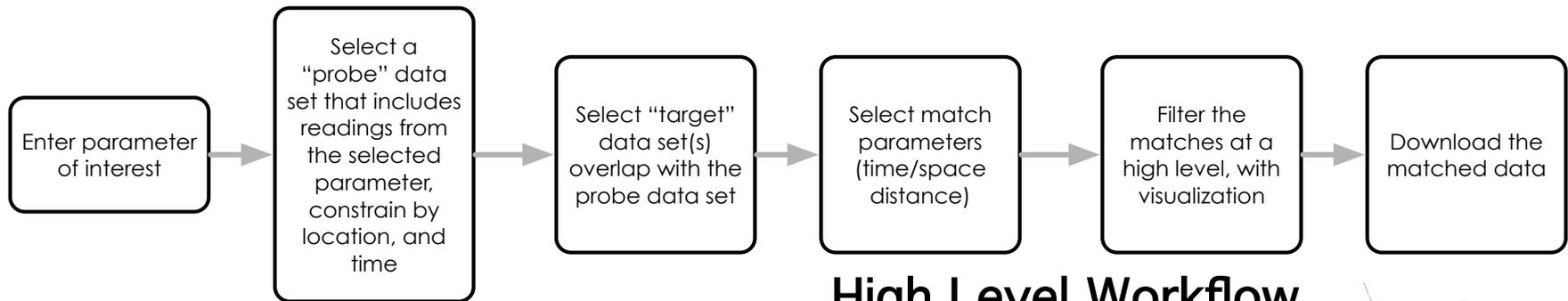
- NASA DAACs with Oceanography focus
 - Supports archival/distribution of extensive collection of satellite data
 - Additionally supporting archival of select NASA-funded *in-situ* datasets
SPURS-1, SPURS-2, Ocean Melting Greenland (OMG)
 - Datasets discoverable via:
 - Web-portal (<https://podaac.jpl.nasa.gov/>) ,
 - NASA ECHO/GCMD, P-WS
 - Data holdings accessible via a range of Tools & Services:
ftp, OPeNDAP, W10n, CWS, THREDDS, LAS, HiTIDE, SOTO, etc.
- DOMS will leverage a range satellite products available from PO.DAAC
 - Prototype will use:
 - SST:
 - GHRSSST-MODIS-A L2P
 - GHRSSST-MODIS-T L2P
 - L4 MUR-SST
 - SSS: L2 Aquarius L2 v3.0
 - Winds: ASCAT L2 25km





User Experience

- DOMS will provide a web portal and web services for users to browse and to submit match-up requests interactively.
 - Presently hosted at JPL
 - Interface will allow users to “test” searches by returning metadata only, then follow with full matched dataset
 - Will support flexible filtering and query specification by:
 - Platform, device, parameter, provider
 - Matchup criteria: spatio-temporal domain (in x,y,z,t) and search radii/tolerances)



High Level Workflow



User Interface Mockups

Select Match Data

Probe Data | **Target Data** | Filter

PROBE DATA SET PARAMETERS

[Surface Temperature] for [SPURS] in [Box Area] [4 Mar 2002] to [29 Jan 2009]

SPATIAL DISTANCE ?
1000 meters

TEMPORAL DISTANCE ?
30 minutes

TARGET DATA SET(S) ?

Satellite *in situ*

MODIS ICOADS
 MUR SAMOS
 Aquarius SPURS
 ASCAT

Visible Color Mission

SPURS-1 *
 MUR
 Aquarius
 SAMOS

FILTER POTENTIAL MATCHES

*should satellites even have a box drawn?
Can we just assume they're all "global" (?) The amount of info will swamp the other boxes...*

Select datasets to match, view overlaps, and set matching tolerences

View matching data statistics and apply filter criteria

Select Match Data

Probe Data | Target Data | **Filter**

MATCH PARAMETERS

[Surface Temperature] in [Box Area] [4 Mar 2002] to [29 Jan 2009] vs Target stuff

PLATFORMS AND MISSIONS INCLUDED ?

	Buoy	Ship	Satellite
SAMOS	<input type="checkbox"/>	<input type="checkbox"/>	-
MUR	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	-
Aquarius	-	-	<input checked="" type="checkbox"/>

DEPTH INCLUDED ? *per mission vs. total only?*

0m | 8m | 25m

QUALITY INCLUDED ?

Poor | Medium | High

CONFIGURE MATCH DOWNLOAD



User Interface Mockups

Select Match Data

Probe Data Target Data Filter

MATCH PARAMETERS

[Surface Temperature] in [Box Area]
[4 Mar 2002] to [29 Jan 2009]
vs
Target stuff

PLATFORMS AND MISSIONS INCLUDED ?

	Buoy	Ship	Satellite
SAMOS	<input type="checkbox"/>	<input type="checkbox"/>	-
MUR	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	-
Aquarius	-	-	<input checked="" type="checkbox"/>

DEPTH INCLUDED ? [per mission vs. total only?](#)

0m 8m 25m

QUALITY INCLUDED ?

Poor Medium High

CONFIGURE MATCH DOWNLOAD

Alternative view of matched data statistics and filter criteria

Data download interface

Download Match Data

SELECTED MATCH PARAMETERS [Edit...](#)

[Surface Temperature] in [Box Area]
[4 Mar 2002] to [29 Jan 2009]
matched to
[SAMOS, MUR, and Aquarius]

ALSO DOWNLOAD CO-INCIDENT... ?

Wind
 Salinity

ESTIMATED TIME TO MATCH DATA
12 minutes

EMAIL ADDRESS FOR NOTIFICATION ?

user@host.edu

START MATCH AND DOWNLOAD

[press this button and it animates into a card below](#)

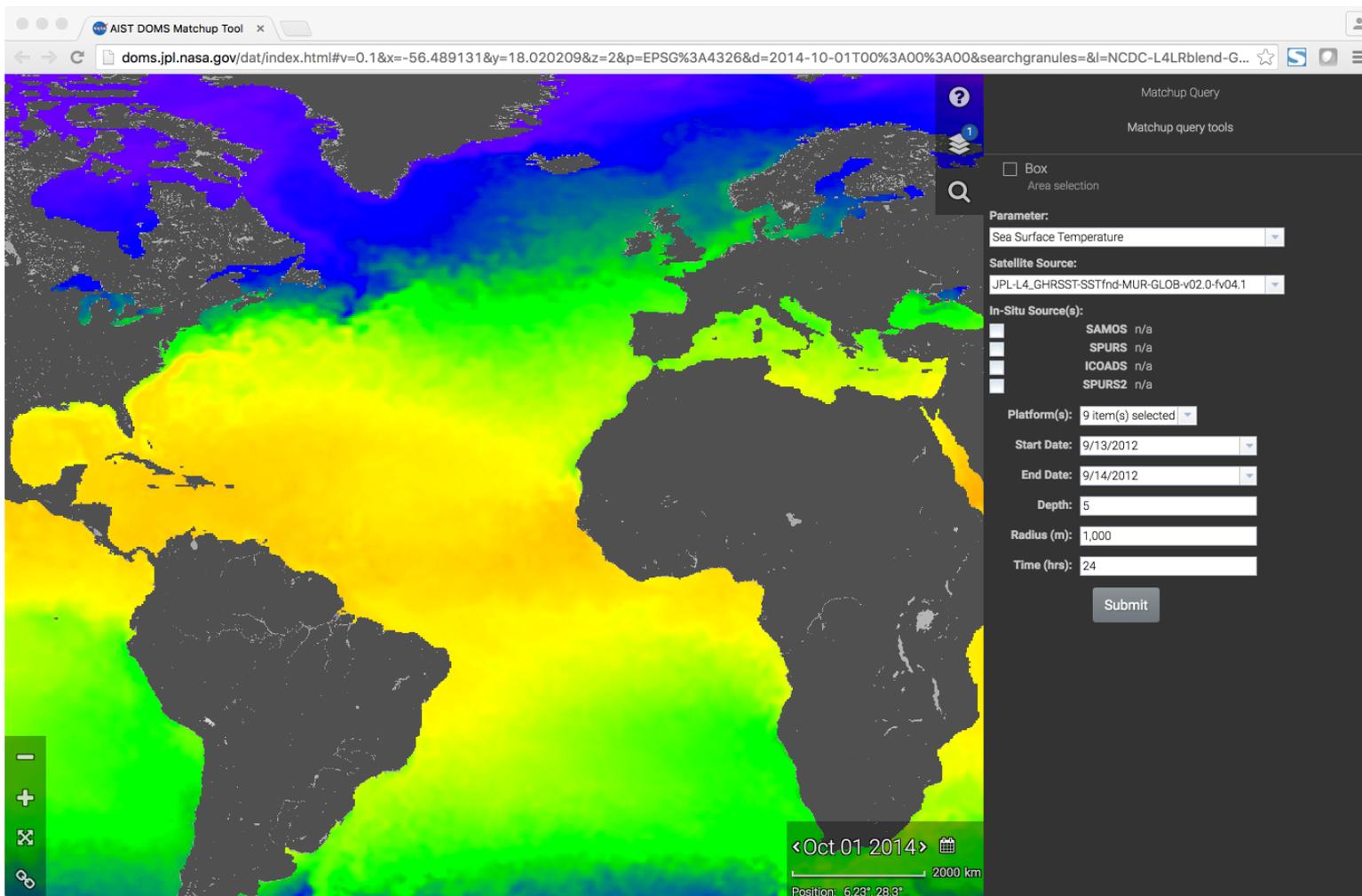
PENDING DATA MATCHES ?

Sea Surface Wind
SAMOS matched to Aquarius, MODIS
4 minutes remaining...



Dynamic Matchup – UI Alpha

High resolution data visualization





Dynamic Matchup – UI Alpha

Initial match according to user initial selection

The screenshot displays the AIST DOMS Matchup Tool interface. The main map area shows a satellite view of the ocean with a central box containing data points. The right sidebar contains a 'Matchup Query' form with the following fields:

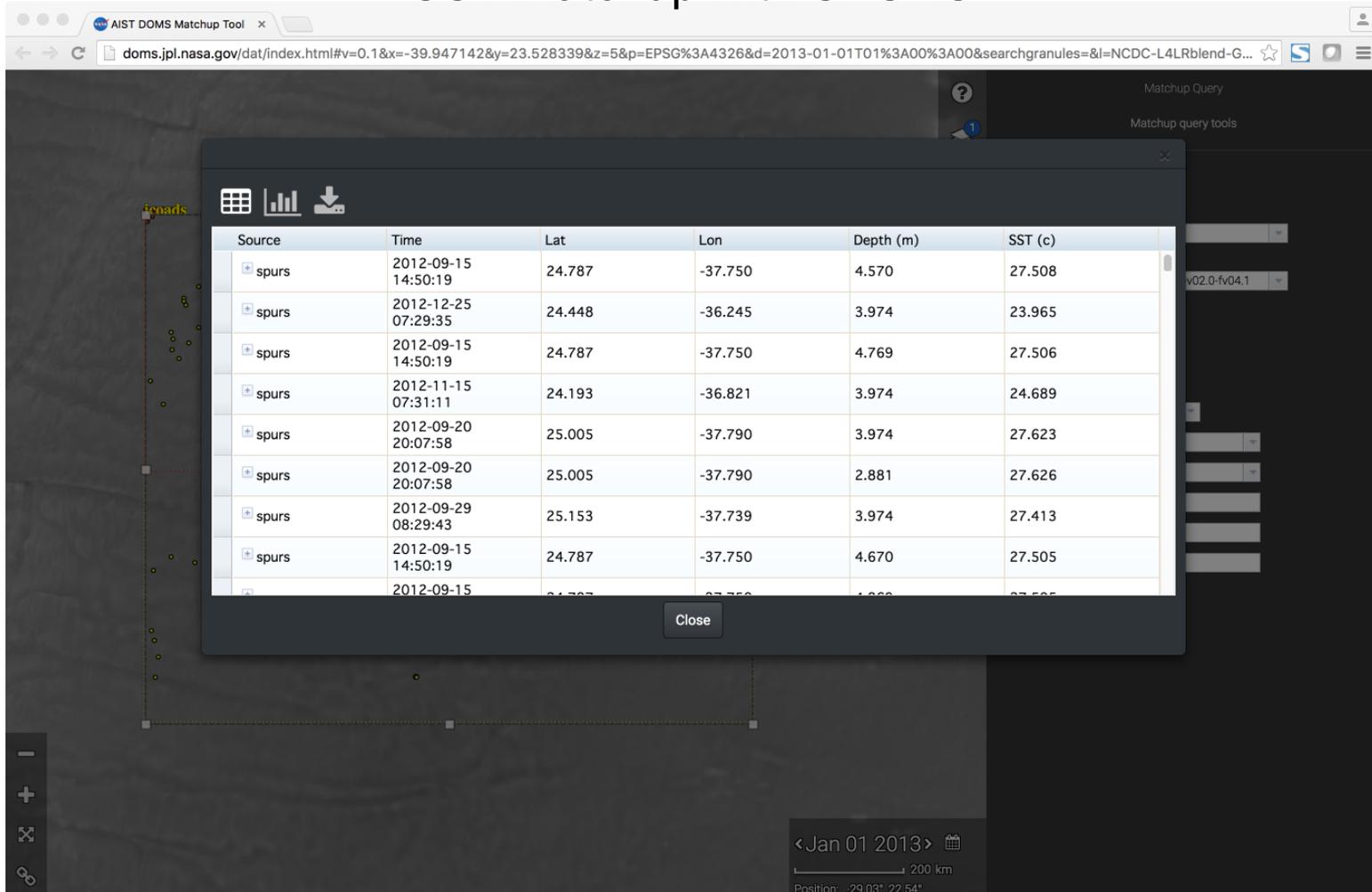
- Matchup Query
- Matchup query tools
- Box Area selection
- Parameter: Sea Surface Temperature
- Satellite Source: JPL-L4_GHRST-SSTfnd-MUR-GLOB-v02.0-fv04.1
- In-Situ Source(s):
 - SAMOS 33090
 - SPURS 73754
 - ICOADS 150066
 - SPURS2 0
- Platform(s): 9 item(s) selected
- Start Date: 9/13/2012
- End Date: 1/1/2013
- Depth: 5
- Radius (m): 1,000
- Time (hrs): 24
- Submit

At the bottom of the map, there is a date selector for '< Jan 01 2013 >' and a scale bar for 200 km. The position is given as -30.42°, 30.07°.



Dynamic Matchup – UI Alpha

SST matchup with SPURS





What's Under the Hood?

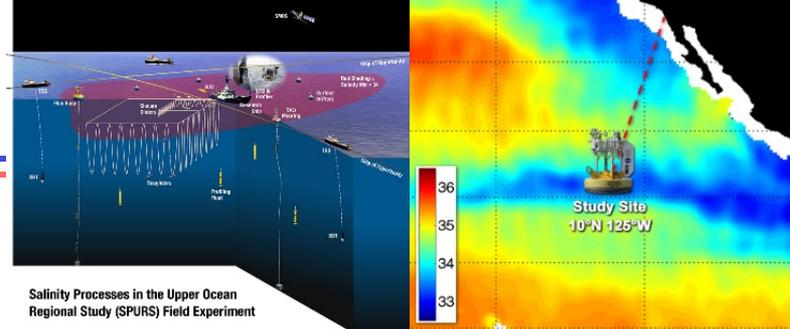
- Each data host (JPL, FSU, NCAR) implemented
 - Apache Solr
 - Used to index data and metadata for common parameters to support search and discovery
 - Index content populated from different backend technology at each host (e.g., MySQL, THREDDS, NoSQL)
 - EDGE
 - Manages queries from central DOMS user interface at JPL to distributed data hosts
- Matching algorithm
 - Hosted by DOMS server at JPL
 - Applies user-specified tolerance criteria to identify “matched” data pairs
 - Returns all pairs for that fall within the space-time tolerance window around each satellite or in-situ value



Looking forward

Supporting SPURS-2 campaign

<http://spurs2.jpl.nasa.gov/>



- JPL group briefed the SPURS data management team (DMT) on DOMS capabilities and provided live demos of functionality
- Two uses for DOMS that can support the field campaign have been jointly identified:
 - Daily in situ and satellite data aggregation and subsetting to provide integrated data extractions for the SPURS2 domain
 - Create daily matchups of available SPURS2 in-situ streams and SST, SMAP-SSS, and/or surface wind satellite data
- SPURS2 data feeds have been identified (ARGO, TAO mooring, drifters) and sample data ingested into DOMS
- Next Steps for DOMS partners and DMT:
 - Establish a standard set of DOMS web-service queries to be executed during the field campaign
 - Ingest JPL SMAP-SSS L2 satellite data & in-situ sample Glider data into DOMS
 - DMT to test and provide further feedback on the DOMS system



Looking Forward

- In 2016 we will continue development of prototype
 - Demonstrations at upcoming meetings (ESIP summer, International Marine Data Information System, AGU)
 - Benchmark and stress testing
 - Documentation
- DOMS will participate in ESIP TRL Testbed from July-Dec 2016
 - Review criteria and team still TBD
 - Goal to provide DOMS team with external review of user experience and assessment of potential for adoption/infusion of DOMS into other programs/agencies



Summary

- A team from FSU, NCAR, and JPL is developing a distributed web portal/service to match in situ and satellite observations
- Prototype will be completed late 2016/early 2017
- Present focus is on
 - User interface (both GUI and web services)
 - Optimizing matching algorithm
 - Testing and reviewing system implementation and operation
 - Expanding application beyond initial cal/val focus



Questions?

Development of DOMS is funded by NASA ESTO via the AIST program under grants to FSU (NNX15AE29G), NCAR (NNX15AG22G), and JPL.

Disclaimer: Any opinions, findings, and conclusions or recommendations provided are those of the contributors to the DOMS project and do not necessarily reflect the views of NASA.

